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Radial Basis Function Networks

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Chapter 5

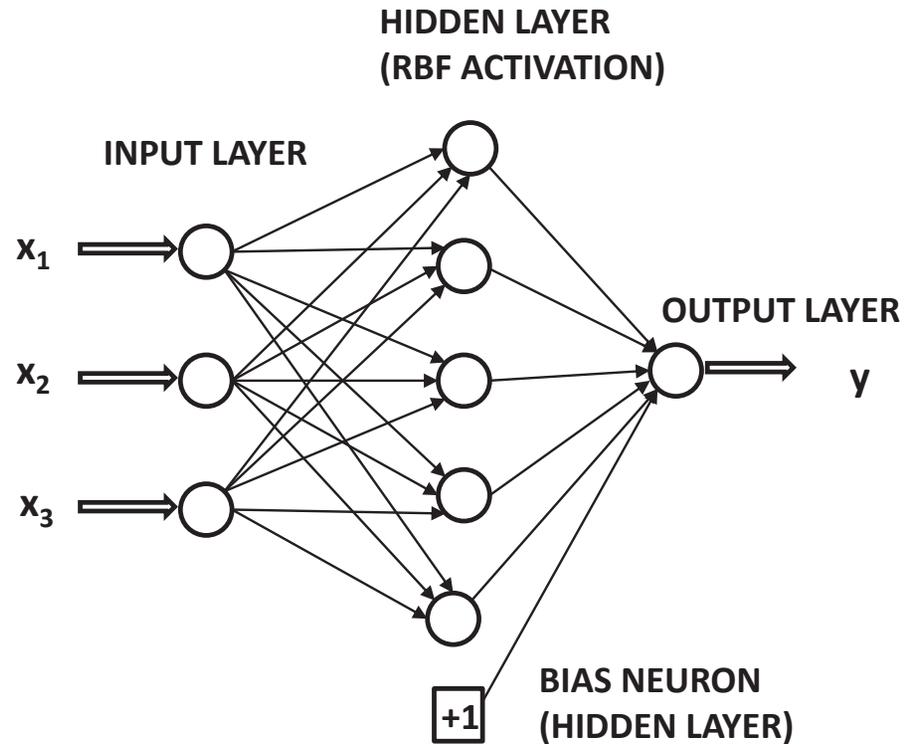
Radial Basis Function Networks

- Radial basis function (RBF) networks represent a fundamentally different paradigm in neural networks.
 - Not deep learners \Rightarrow Often a single *unsupervised* hidden layer is used.
 - Deep learners represent an exercise in supervised feature engineering.
- RBF networks are closely related to SVMs.
 - SVMs represent a special case of RBF networks.
 - Like SVMs, RBF networks are universal function approximators.

When to Use RBF Networks

- Deep networks work best when the data has rich structure (e.g., images).
 - Property of hierarchical and supervised feature engineering.
- RBF networks are best when the data is noisy (but structure is less intricate).
 - Unsupervised feature engineering is robust to noise.

RBF Network



- Single (unsupervised) hidden layer with high dimensionality $m \gg d$ and linear output layer.
- Each hidden unit contains a prototype vector and activation depends on similarity of input to prototype (kernel similarity!).

Workings of the RBF Network

- Each of m hidden units has its own prototype vector $\bar{\mu}_i$ and bandwidth σ_i .
 - Common to set each $\sigma_i = \sigma$.

- For input vector \bar{X} , activation h_i of i th hidden unit (no weights!):

$$h_i = \Phi_i(\bar{X}) = \exp\left(-\frac{\|\bar{X} - \bar{\mu}_i\|^2}{2 \cdot \sigma_i^2}\right) \quad \forall i \in \{1, \dots, m\} \quad (1)$$

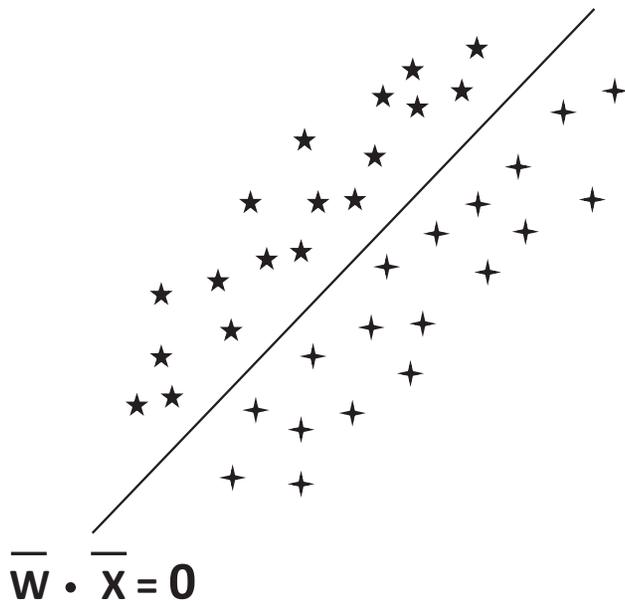
- Output layer is linear classifier/regressor with weights w_i .

$$\hat{y} = \sum_{i=1}^m w_i h_i \quad [\text{Real-valued outputs}]$$

How do RBF Networks Classify Nonlinearly Separable Classes?

- Work on Cover's principle of separability of patterns.
- Transforming low-dimensional data to high-dimensional space leads to greater ease in linear separation.
- The prototypes define local influence regions of the space.
 - Each feature corresponds to a local region.
- The final layer puts each region on the appropriate side of the separator.

Illustration of Separation Process



LINEARLY SEPARABLE IN
INPUT SPACE

ONE HIDDEN UNIT FOR EACH CLUSTER

$(a, 0, 0, 0)$



$(0, 0, 0, d)$



$(0, b, 0, 0)$



$(0, 0, c, 0)$



NOT LINEARLY SEPARABLE IN INPUT SPACE BUT
SEPARABLE IN 4-DIMENSIONAL HIDDEN SPACE

- One prototype from each cluster.
- Each local region is mapped to its own feature with a possible linear separator as $\bar{W} = [1, -1, 1, -1]$.

Training an RBF Network

- Training works in two phases:
 - Learn the prototype vectors $\bar{\mu}_i$ and bandwidth σ in an unsupervised manner.
 - Learn the weights of the output layer in supervised manner.
 - * Straightforward training of single-layer network with engineered features.

Training the Hidden Layer

- Only need to find the prototype vectors $\bar{\mu}_i$ and bandwidth σ .
 - The prototypes can be sampled from data or can be centroids of clusters.
- Let d_{max} be maximum distance between pairs of prototypes and d_{ave} be average distance.
 - Two heuristic choices of σ are d_{max}/\sqrt{m} and $2 \cdot d_{ave}$.
 - The bandwidth can also also be tuned on validation data.

Kernel Methods are Special Cases of RBF Networks

- Set the prototypes to all data points and:
 - Linear output layer (squared loss) for kernel regression/Fisher discriminant.
 - Linear output layer (hinge loss) for SVM
 - Logistic output layer (log loss) for kernel logistic regression
- Proofs in book.

Are Supervised Methods Any Good?

- Supervised training methods for hidden layer discussed in book.
- Generally, supervision of hidden layer leads to overfitting.
 - Supervised feature engineering is generally done by deep networks.
 - RBF networks are too shallow!
 - RBF prototype/bandwidth parameters have too complicated a loss surface to be learned in a supervised manner.
- Only mild forms of supervision desirable (e.g., tuning σ or mildly supervised prototype collection).